

**BACnet® communication module for TCX2: AEX-BAC**

**Features**

- BACnet® MS/TP communication over RS485
- B-ASC device profile
- Slave type of communication
- Supports up to 127 nodes on one network
- Galvanic isolated bus connection
- Baudrates: Auto / 9600 / 19200 / 38400 / 57600 / 76800 / 115200
- LED indicators

**TCX2-BAC Protocol Implementation Conformance Statement (PICS)**

Vendor name: Vector Controls  
 Product name: TCX2 Controls series  
 TCX2 product description:  
 The TCX2 communicating BACnet® controllers are designed as universal controls equipment suitable for a large number of applications. They may be used in zoning and other applications which are monitored by a BACnet® MS/TP network.

**Supported BACnet® Interoperability Blocks (BIBB)**

The BACnet® interface conforms to the B-ASC device profile (BACnet® Application Specific Controller). The following BACnet® Interoperability Building Blocks (BIBB) are supported.

BIBB	Type	Name
DS-RP-B	Data sharing	Read property - B
DS-RPM-B	Data sharing	Read property multiple - B
DS-WP-B	Data sharing	Write property - B
DM-DCC-B	Device management	Device communication control - B
DM-DOB-B	Device management	Dynamic device binding - B
DM-DOB-B	Device management	Dynamic object binding - B
DM-TS-B	Device management	Time synchronisation - B
DM-UTC-B	Device management	UTC time synchronization - B
DM-RD-B	Device management	Reinitialize device - B

**Supported standard BACnet® application services**

- ReadProperty
- ReadPropertyMultiple
- WriteProperty
- DeviceCommunicationControl. Needs a password which is "Vector" (case sensitive an without the quotes)
- I-Am
- I-Have
- TimeSynchronisation
- UTCTimeSynchronization
- ReinitializeDevice ("cold" or "warm")  
Needs a password which is "Vector" (case sensitive an without the quotes)

**Supported standard object types**

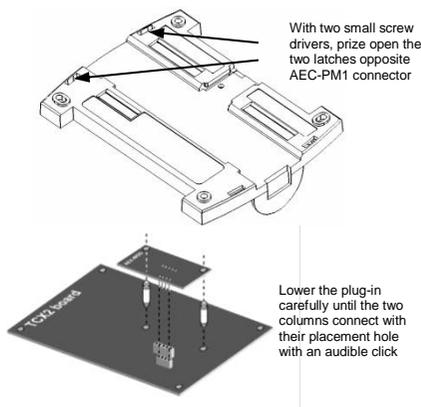
- Device
- Analog input
- Analog value
- Binary value
- Multi-state value

**Assembly**

The steps outlined below are only required if the communication plug in is to be added to a standalone controller. A clean and ESD compliant working environment is required. If you are unsure about this procedure, contact your nearest dealer.

- Disconnect all wires from the controller and remove it from its mounted position
- Turn controller around:

- Carefully separate the lower housing from the upper housing,
- Insert the two columns first into the large holes on either corner of the AEX-BAC
- Then match the two connectors of the AEX-BAC with their counterparts of the main board.

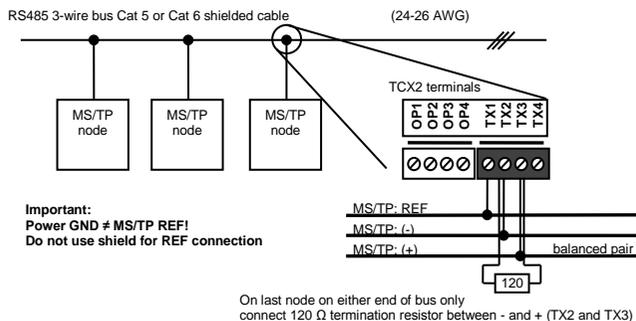


- Bend the two latches of the upper part slightly outwards and re-assemble the upper part with the lower part of the housing. Make sure the four latches connect save and the housing is secured.

**Technical specification**

Power supply	Power requirements	5 VDC ± 5%
	Power consumption	Max. 2 VA
Network	Hardware interface	RS485 in accordance with EIA/TIA 485
	Max nodes per network	127
	Max nodes per segment	64 (Vector devices only)
	Cabling	Twisted Shielded Pair (TSP) cable category 5 or 6, balanced 120 ohm
	Impedance	100 pF/m 16pF/ft or lower
	Nominal capacitance	65% or higher
Galvanic isolation	Galvanic isolation	The communication circuitry is galvanic isolated
	Line termination	A line termination resistance (120 Ω) shall be connected between the terminals - (TX2) and + (TX3) of the furthestmost node of the network
	Fail-safe biasing	The device supports fail-safe biasing
BACnet®	Network topology	Daisy chain according EIA/TIA 485 specifications
	Maximum length per chain	1200 m (4000 ft.)
	Communication standard	BACnet® MS/TP Master on RS485
Environment	Default setting	Auto
	Communication speed	Auto, 9600, 19200, 38400, 57600, 76800, 115200
	Operation	To IEC 721-3-3 class 3K5
	Climatic conditions	0...50 °C (32...122 °F)
	Temperature	< 95 % RH non-condensing
	Humidity	To IEC 721-3-2 and IEC 721-3-1 class 3K3 and class 1K3
Standards	Transport & storage	-25...70 °C (-13...158 °F)
	Climatic conditions	< 95 % RH non-condensing
	Humidity	class 2M2
Standards	Mechanical conditions	2004/108/EC
	CE conformity	EMC Directive
	Product standards	Automatic electrical controls for household and similar use
	Automatic electrical controls for household and similar use	EN 60730-1
	Special requirement on temperature dependent controls	EN 60730-2-9
	Electromagnetic compatibility for industrial and domestic sector	Emissions: EN 60730-1 Immunity: EN 60730-1

**Bus connection**



**Fail-safe biasing:**  
 The device supports fail-safe biasing (line polarization). 680 Ω per wire, maximum 1 set per RS485 segment.  
**Shield connection:**  
 The shield of the wire must not be used to connect to the REF terminal. Connect all the shields together and ground in one single point on the network. Make sure the shields do not accidentally touch the ground.  
 Multiple ground connections induce noise and affect communication.

**LED indicators**

The BACnet® interface features a green LED for indication of traffic on the RS-485 bus. The green LED is lit when an incoming packet is received, and the red LED is lit when an outgoing packet is transmitted to the bus. At power-up, both LED blink twice simultaneously as a sign of the boot process being completed. A constantly lit LED serves as an indication of a fault condition in the reception or sending process.

**Configuration of AEX-BAC**

The communication parameters may be set via TCX2-OP controllers or OPA2 terminals once the device is plugged in the TCX2 base. Login to the controller as follows:

1. Press UP/DOWN buttons simultaneously for three seconds. The display will show firmware version and revision number. Press the OPTION button to start login.
2. CODE is shown in small display.
3. Select 241 using UP/DOWN buttons.
4. Press OPTION after selecting the correct code.
5. Once logged in with 241 control modules are displayed (Lp1, Lp2, 1u, 2u, etc.) – select with UP/DOWN the communication parameters CO and open with OPTION. As soon as the module is open its parameters are displayed.
6. Select the parameters with the UP/DOWN buttons. Change a parameter by pressing the OPTION button. Three arrows are displayed to indicate that the parameter may be modified. Use UP/DOWN buttons to adjust the value.
7. After you are done, press OPTION to save the new value and return to the selection level (arrows disappear when selection is pressed). Pressing left hand POWER button without pressing OPTION will discard the value and return without saving. For control parameters press POWER again to leave parameter selection and return to control module selection.
8. Press the POWER to leave the menu. The unit will return to normal operation if no button is pressed for more than 5 minutes.

**COM parameters**

Parameter	Description	Range	Default
CO 00	Bus plug-in hardware id (read only)	0...255	3
CO 01	Bus plug-in software version (read only)	0...255	-
CO 02	Bus plug-in software revision (read only)	0...255	-
CO 03	Communication address (must be unique in network)	1...127	1
CO 04	Baud rate: 0 = Auto-detect <sup>1</sup> 1 = 9600 2 = 19200 3 = 38400 4 = 57600 5 = 76800 6 = 115200	0...5	0 (Auto-detect)
CO 05	Highest master	0...127	127
CO 06	Device object ID1 000000xx	0...99	03
CO 07	Device object ID2 0000xx00	0...99	43
CO 08	Device object ID3 00xx0000	0...99	19
CO 09	Device object ID4 0x000000	0...4	4
CO 10	Send I-am at boot	1, 0 (ON, OFF)	ON
CO 11	Not used	0...255	255
CO 12	Not used	0...255	255
CO 13	Not used	0...255	255
CO 14	Not used	0...255	255
CO 15	Auto-increment <sup>2</sup> and auto-build <sup>3</sup> of "device object name" flags: 0 = Auto-increment and auto-build of device object name disabled 1 = Auto-increment is enabled, auto-build of device object name disabled 2 = Auto-increment disabled, auto-build of device object name enabled 3 = Auto-increment and auto-build of device object name enabled	0...3	2

<sup>1</sup> "Auto-detect baud rate"-mode

When this option is selected, the AEC-BAC will detect the baud rate of the RS485 network. The AEX-BAC will stay in baud rate detection mode until it successfully decodes a package sent with a baud rate which is supported by the AEX-BAC. The baud rate detection mode will be entered once at hardware start-up and after a prolonged communication failure.

<sup>2</sup> "Auto-increment"-function

When this function is enabled and an automatic AEC-PM1 parameter load is executed at power up of the controller, the following variables will be incremented and written back to the AEC-PM1 unit:  
 - CO 03 Communication address. This is incremented only if the value is not already 127 with respect to CO 05 - the address of the highest master. If CO 05 is equal or less than the newly incremented value of CO 03, then CO 05 is written to be 127 (the maximum value of CO 05 possible).  
 - CO 06...CO 09 Device object ID. This is incremented only if the value is not already "4194304".

<sup>3</sup> "Auto-build of device object name"-function

The BACnet standard requires that each BACnet endpoint has a unique name on the network (device object name). The initial name of the AEX-BAC module is "AEX-BAC" equal for all devices. This means that device object names need to be edited manually.  
 Using the auto-build-function the device object name can be automatically assembled using the label AEX-BAC followed by the contents of CO 06...CO 09 (the device object ID). For example AEX-BAC-01050001.  
 If one writes the device object name manually through BACnet, the auto-build function will automatically be disabled (CO 15 set to 0 or 1).  
 In this case, the auto increment function will not have an effect on the device object name, only on the device object ID.

**Product documentation**

Download the latest product documentation including description of objects as well as dynamic and static values online:  
 English international: [www.vectorcontrols.com/download/AEX/70-00-0218\\_AEX-BAC\\_V1-2.pdf](http://www.vectorcontrols.com/download/AEX/70-00-0218_AEX-BAC_V1-2.pdf)  
 English US: [www.vectorcontrols.com/download/AEX/70-07-0218\\_AEX-BAC\\_V1-2.pdf](http://www.vectorcontrols.com/download/AEX/70-07-0218_AEX-BAC_V1-2.pdf)  
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