

Modbus communication module for TCX2: AEX-MOD

AEX-MOD



TCX2

AEX-MOD is factory installed in TCX2 series controllers with -MOD suffix, and is also available separately upon request for customer installation in standard TCX2 series controllers.

Features

- RS485 2-wire MODBUS standard in accordance with EIA/TIA 485.
- Slave type of communication
- Supports up to 127 nodes on one network
- Galvanic isolated bus connection
- LED indicators
- Selectable transmission types:
 - **RTU** with CRC16 checksum
 - ASCII with LRC checksum
 - Baud rates: 4800, 9600, **19200**, 38400
 - Parity: No parity, odd or **even parity**.
 - Default: RTU with 8 data bits, 1 even parity bit, 1 stop bit. Baud rate 19200.

Communication Specification

| | |
|------------------------|----------------------------------------------------------------|
| Communication standard | Modbus (www.modbus.org) |
| Default setting | 19200 Baudrate, RTU 8 data bits, 1 even parity bit, 1 stop bit |
| Communication speed | 4800, 9600, 19200, 38400 |
| Protocol | RTU with CRC16 checksum ASCII with LRC checksum |
| Parity bit | no parity, even parity, odd parity |

By **default**, **RTU** uses 8 data bits, 1 parity bit with even parity and 1 stop bit; ASCII mode uses 7 data bits, 1 parity bit with even parity, and 1 stop bit.

Both modes support "No Parity" mode, in these cases a 2nd stop bit is used to keep the byte length (11bit for RTU and 10 bit for ASCII, including the Start and Stop bits) unchanged in accordance with the Modbus specification. Other possible serial port modes like Odd Parity or baud rates other than listed ones are not supported.

Supported Modbus commands:

- 03 (0x03): Read multiple registers
- 06 (0x06): Write single register
- 16 (0x10): Write multiple registers

In commands 03 and 16 the allowed number of registers ranges from 1 to 32. Although Modbus specification would allow more registers to be read and written, a maximum of 32 Modbus registers are supported in one packet. One Modbus register is 16 bits wide. The Modbus slave transmits the values as signed 16 bit integers. The least significant digit of the transmitted number is always the first digit below the decimal point, and this results in the following range of numbers that the slave module is able to transmit: from -9999.9 to 9999.9

In an event of an out-of-range command addressing or an unsupported command, the Modbus slave responds with an exception message according to the Modbus specification.

LED indicators

The Modbus slave features a green LED and a red LED for indication of traffic on the RS-485 bus. The green LED is lit when an incoming packet is received, and the red LED is lit when an outgoing packet is transmitted to the bus. At power-up, both LED blink twice simultaneously as a sign of the boot process being completed. A constantly lit LED serves as an indication of a fault condition in the reception or sending process.


Ordering

AEX-MOD is pre-installed in TCX2-40863-MOD and TCX2-40863-OP-MOD as well as any other -MOD TCX2 configuration.

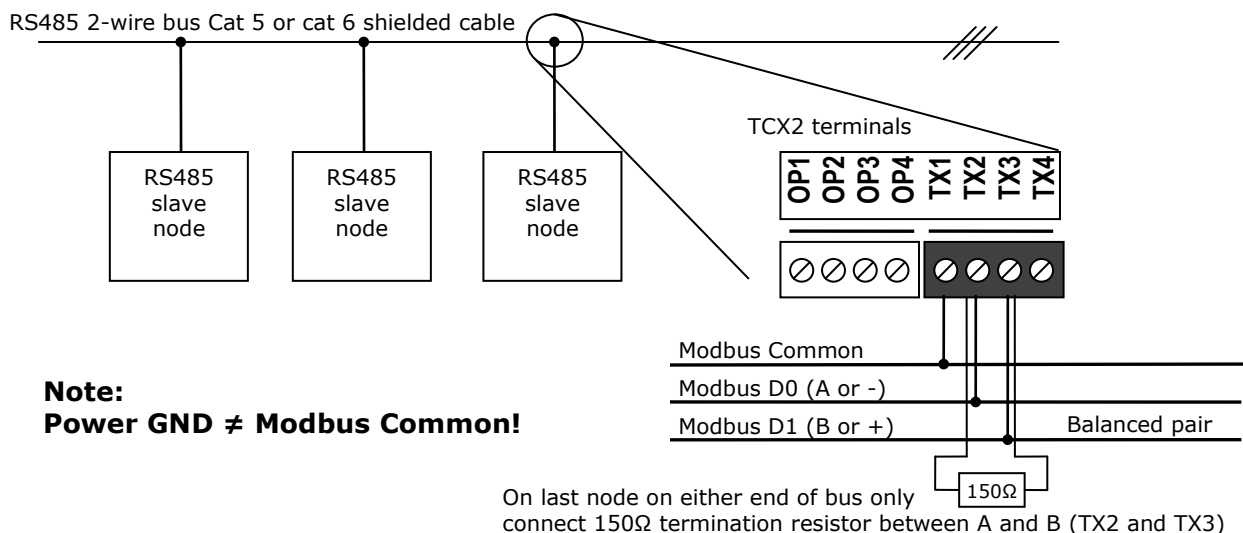
| Model | Item# | Display | Loop | UI/RT | DO | AO | Description |
|-------------------|------------|---------|------|-------|----------|----|-------------------------------------|
| TCX2-40863 | 40-11 0032 | no | 4 | 8 UI | 6 Relays | 3 | Universal controller stand-alone |
| TCX2-40863-OP | 40-11 0036 | Yes | 4 | 8 UI | 6 Relays | 3 | Controller with display stand-alone |
| TCX2-40863-MOD | 40-11 0077 | no | 4 | 8 UI | 6 Relays | 3 | Universal controller with Modbus |
| TCX2-40863-OP-MOD | 40-11 0078 | Yes | 4 | 8 UI | 6 Relays | 3 | Controller with display and Modbus |
| TCX2-14050-MOD | 40-11 0081 | no | 1 | 4 RT | 5 Relays | 0 | Universal controller with Modbus |
| TCX2-14050-OP-MOD | 40-11 0082 | Yes | 1 | 4 RT | 5 Relays | 0 | Controller with display and Modbus |
| AEX-MOD | 40-50 0013 | - | - | - | - | - | Modbus communication module |

Technical specifications

Notice! Failure to follow specifications and local regulations may cause equipment damage. Misapplication will void warranty.

| | | |
|---------------------|-------------------------------------------------------------------------------------------------------------|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------|
| Power Supply | Power Requirements | 5VDC $\pm 5\%$, 10mA max. |
| Network | Hardware interface | 2-wire Modbus over RS485 in accordance with EIA/TIA 485 |
| | Max nodes | 127 devices may be connected on one network |
| | Cabling | Twisted Shielded Pair (TSP) cable category 5 or 6. |
| | Impedance | balanced 100 to 120 ohm |
| | Nominal Capacitance | 50 pF/m 16pF/ft or lower |
| | Nominal Velocity | 65% or higher |
| | Galvanic Isolation | The output circuitry of the AEX-BAC module is galvanic isolated. |
| Modbus | Line termination | A line termination resistance (150 ohm) shall be connected between the terminals A and B of the furthestmost slave (relatively from the Modbus master) node of the network |
| | Line polarization | The device needs polarization. |
| | Communication standard | Modbus (www.modbus.org) |
| | Default setting | 19200 Baud rate, RTU 8 data bits, 1 even parity bit, 1 stop bit |
| | Communication speed | 4800, 9600, 19200, 38400 |
| | Protocol | RTU with CRC16 checksum ASCII with LRC checksum |
| | Parity bit | no parity, even or odd parity |
| Environment | Operation Climatic Conditions | To IEC 721-3-3 class 3 K5 |
| | Temperature | 0...50 °C (32...122 °F) |
| | Humidity | <95 % r.H. non-condensing |
| | Transport & Storage Climatic Conditions | To IEC 721-3-2 and IEC 721-3-1 class 3 K3 and class 1 K3 |
| | Temperature | -25...70 °C (-13...158 °F) |
| | Humidity | <95 % r.H. non-condensing |
| | Mechanical Conditions | class 2M2 |
| Standards |  conformity EMC Directive | 2004/108/EC |
| | Low Voltage Directive | 2006/95/EC |
| | Product standards | |
| | Automatic electrical controls for household and similar use | EN 60 730 -1 |
| | Special requirement on temperature dependent controls | EN 60 730 - 2 - 9 |
| | Electromagnetic compatibility for industrial and domestic sector | Emissions: EN 60 730-1 Immunity: EN 60 730-1 |

Wiring



Line polarization:

The device needs line polarization. One pair of resistors may be connected on the RS-485 balanced pair:

- a Pull-Up Resistor to a 5V Voltage on D1 circuit,
- a Pull-Down Resistor to the common circuit on D0 circuit. This should be done only once at the master only. The value of those resistors must be between 450 Ohms and 650 Ohms. 650 Ohms resistors value may allow a higher number of devices on the serial line bus.

Configuration of AEX-MOD

The communication parameters may be set via TCX2-OP controllers or OPA2 terminals once the device is plugged in the TCX2 base. Login to the controller as follows:

1. Press UP/DOWN buttons simultaneously for three seconds. The display will show firmware version and revision number. Press the OPTION button to start login.
2. CODE is shown in small display.
3. Select 241 using UP/DOWN buttons.
4. Press OPTION after selecting the correct code.
5. Once logged in with 241 control modules are displayed (Lp1, Lp2, 1u, 2u, etc.) – select with UP/DOWN the communication parameters **CO** and open with OPTION. As soon as the module is open its parameters are displayed.
6. Select the parameters with the UP/DOWN buttons. Change a parameter by pressing the OPTION button. Three arrows are displayed to indicate that the parameter may be modified. Use UP/DOWN buttons to adjust the value.
7. After you are done, press OPTION to save the new value and return to the selection level (arrows disappear when selection is saved). Pressing left hand POWER button without pressing OPTION will discard the value and return without saving. For control parameters press POWER again to leave parameter selection and return to control module selection.

Press the POWER to leave the menu. The unit will return to normal operation if no button is pressed for more than 5 minutes.

COM parameters

| Parameter | Description | Range | Default |
|-----------|-----------------------------------------------------------------------------------------------------------------------|---------|---------|
| CO 00 | Bus plug-in id (read only) | 0...255 | - |
| CO 01 | Bus plug-in software version (read only) | 0...255 | - |
| CO 02 | Bus plug-in software revision (read only) | 0...255 | - |
| CO 03 | Communication address (must be unique in network) | 1...247 | 1 |
| CO 04 | Baud rate: 0 = 19200 1 = 4800 2 = 9600 3 = 19200 4 = 38400 | 0...255 | 0 |
| CO 05 | Parity mode 0 = NO Parity 1 = EVEN Parity 2 = ODD Parity | 0...255 | 1 |
| CO 06 | Mode of communication 0 = RTU 1 = ASCII | 0...255 | 0 |
| CO 07 | Allow changing of static settings through communication 0 = Not allowed 1 = Allowed | 0...255 | 1 |
| CO 08 | Modbus address base mode 0 = Modbus addresses are "Base 0" 1 = Modbus addresses are "Base 1" (PLC style) | 0...255 | 0 |
| CO 09 | User definable data storage address 00 | 0...255 | 255 |
| CO 10 | User definable data storage address 01 | 0...255 | 255 |
| CO 11 | User definable data storage address 02 | 0...255 | 255 |
| CO 12 | User definable data storage address 03 | 0...255 | 255 |

Dynamic Address list

Controller information

| Address | Description | Range | R/W |
|---------|-------------------------------------------|-------|-----|
| 1000 | Product series information | 8Bit | R |
| 1001 | Product type information | 8Bit | R |
| 1002 | Controller Firmware Version | 8bit | R |
| 1003 | Controller Firmware Revision | 8bit | R |
| 1004 | Type of controller | 16bit | R |
| 1005 | Number of control loops | 16bit | R |
| 1006 | Number of binary inputs | 16bit | R |
| 1007 | Number of universal inputs | 16bit | R |
| 1008 | Number of virtual inputs | 16bit | R |
| 1009 | Number of binary outputs | 16bit | R |
| 1010 | Number of analog outputs | 16bit | R |
| 1011 | Number of fan outputs | 16bit | R |
| 1012 | Number of floating outputs | 16bit | R |
| 1013 | Number of alarms | 16bit | R |
| 1014 | Number of auxiliary functions | 16bit | R |
| 1015 | Number of time schedules | 16bit | R |
| 1016 | Number of switching times / time schedule | 16bit | R |

Controller state

| | | | |
|------|--------------------------------------------------------------------------------------------------------|------------|-----|
| 1050 | Operation State ON 0 = OFF, 1 = ON | 1bit | R/W |
| 1051 | Operation state Standby – Comfort 0 = Comfort , 1 = Standby | 1bit | R/W |
| 1052 | Operation State Heat – Cool 1 = Heat , 0 = Cool | 1bit | R/W |
| 1053 | Operation state Celsius – Fahrenheit 0 = Celsius , 1 = Fahrenheit | 1bit | R/W |
| 1054 | Operation state Fan Only 0 = Fan Only disabled 1 = Fan Only enabled | 1bit | R/W |
| 1055 | Operation state Enable Time Schedules 0 = Time Schedules disabled 1 = Time Schedules enabled | 1bit | R/W |
| 1080 | Year (0...99) (future feature) | BCD format | R/W |
| 1081 | Month (1...12) (future feature) | BCD format | R/W |
| 1082 | Day (1...31) (future feature) | BCD format | R/W |
| 1083 | DoW (Day of the week 1...7) | BCD format | R/W |
| 1084 | Hour (00...23) | BCD format | R/W |
| 1085 | Minute (00...59) | BCD format | R/W |
| 1086 | Second (00...59) | BCD format | R/W |
| 1099 | Broadcast packet network address change enable bit* | 1bit | R/W |

Changing address of controller through broadcast message:

* Address "1099" needs to be written to "1", if the ModBus master wants that the ModBus slave(s) accept the broadcast packet and value in the special case of the ModBus network address change. Trying to change the network address with a broadcast packet to its address ("13003") without writing "1" to address "1099" first will result in the value being not changed at register address "13003". The value of register at address "1099" can be read and written any time. At power-up, its value is "0". Every time a read or write of another register at any other address is performed, the value of register at address "1099" gets re-set to "0". This procedure prevents accidental broadcast messages to be accepted to set the network address of each node to the same value. Only the specific sequence of actions – as listed above – will result in a successful change of network address with a broadcast message. Please note that normal *addressed* writes to register at address "13003" will work without limitation or the requirement of specific sequence of events.

Inputs

| Address | Input | Description | Range | R/W |
|---------|-------|--------------------------------------------------------------------------------------------------------------------------------------------------------------|-------|-----|
| 1100 | UI1 | universal input 1 state, 0 = not active / error, 1 = ok | Bit | R |
| 1101 | UI1 | Unit of universal input 0 = no unit 1 = % 2 = °C / °F 3 = Pa | 8bit | R |
| 1102 | UI1 | Value Multiplier: "1" means a multiplication factor of 0.1 "10" means a multiplication factor of 1 "100" means a multiplication factor of 10 | 8bit | R |
| 1103 | UI1 | Value | 16bit | R |
| 1104 | UI2 | universal input 2 state, 0 = not active / error, 1 = ok | Bit | R |
| 1105 | UI2 | Unit of universal input (explanation as in 1101) | 8bit | R |
| 1106 | UI2 | Value Multiplier (explanation as in 1102) | 8bit | R |
| 1107 | UI2 | Value | 16bit | R |
| 1108 | UI3 | universal input 3 state, 0 = not active / error, 1 = ok | Bit | R |
| 1109 | UI3 | Unit of universal input (explanation as in 1101) | 8bit | R |
| 1110 | UI3 | Value Multiplier (explanation as in 1102) | 8bit | R |
| 1111 | UI3 | Value | 16bit | R |
| 1112 | UI4 | universal input 4 state, 0 = not active / error, 1 = ok | Bit | R |
| 1113 | UI4 | Unit of universal input (explanation as in 1101) | 8bit | R |
| 1114 | UI4 | Value Multiplier (explanation as in 1102) | 8bit | R |
| 1115 | UI4 | Value | 16bit | R |
| 1116 | UI5 | universal input 5 state, 0 = not active / error, 1 = ok | Bit | R |
| 1117 | UI5 | Unit of universal input (explanation as in 1101) | 8bit | R |
| 1118 | UI5 | Value Multiplier (explanation as in 1102) | 8bit | R |
| 1119 | UI5 | Value | 16bit | R |
| 1120 | UI6 | universal input 6 state, 0 = not active / error, 1 = ok | Bit | R |
| 1121 | UI6 | Unit of universal input (explanation as in 1101) | 8bit | R |
| 1122 | UI6 | Value Multiplier (explanation as in 1102) | 8bit | R |
| 1123 | UI6 | Value | 16bit | R |
| 1124 | UI7 | universal input 7 state, 0 = not active / error, 1 = ok | Bit | R |
| 1125 | UI7 | Unit of universal input (explanation as in 1101) | 8bit | R |
| 1126 | UI7 | Value Multiplier (explanation as in 1102) | 8bit | R |
| 1127 | UI7 | Value | 16bit | R |
| 1128 | UI8 | universal input 8 state, 0 = not active / error, 1 = ok | Bit | R |
| 1129 | UI8 | Unit of universal input (explanation as in 1101) | 8bit | R |
| 1130 | UI8 | Value Multiplier (explanation as in 1102) | 8bit | R |
| 1131 | UI8 | Value | 16bit | R |
| 1132 | VI9 | universal input 9 state, 0 = not active / error, 1 = ok | Bit | R |
| 1133 | VI9 | Unit of universal input (explanation as in 1101) | 8bit | R |
| 1134 | VI9 | Value Multiplier (explanation as in 1102) | 8bit | R |
| 1135 | VI9 | Value | 16bit | R/W |
| 1136 | VI10 | universal input 10 state, 0 = not active / error, 1 = ok | Bit | R |
| 1137 | VI10 | Unit of universal input (explanation as in 1101) | 8bit | R |
| 1138 | VI10 | Value Multiplier (explanation as in 1102) | 8bit | R |
| 1139 | VI10 | Value | 16bit | R/W |

Virtual inputs

The TCX2 can operate with external inputs. To activate, program the virtual input to use it as external input of the communication module: for example 9u00 = 2 (Address 3800 = 2) or 10u00 = 2 (Address 3900 = 2, see static address list on page 8).

Set minimum and maximum display value, unit and multiplication according the inputs requirement in the universal input parameters of the TCX2.

Then program the master to write in not less than 60 seconds intervals the value to the dynamic address of the corresponding input. The time out for universal inputs is set to 130 seconds. The initial startup delay is 200 seconds. The value address for UI9 for example is 1135, for UI10 it is 1139.

Exceeding the timeout will lead to the universal input to be disabled. If the input is assigned as control input, the configuration error ERR4 will be displayed. Re-writing to the universal input, will re-enable the input but will not clear error 4. Error 4 may only be cleared by switching the controller on and off or by pressing the OPTION key with the key pad.

The ID of the virtual input follows after the physical inputs. For example a controller with 8 universal inputs and 2 virtual inputs would have the virtual inputs as address 9 and 10.

Control loop

| Address | Loop | Description | Range | R/W |
|---------|--------|------------------------------------------------|-------|-----|
| 1200 | Loop 1 | Control input state | 8Bit | R |
| 1201 | Loop 1 | Control loop sequence 1 = heating, 0 = cooling | 1bit | R |
| 1202 | Loop 1 | Control input unit | 8 bit | R |
| 1203 | Loop 1 | Control input value | 16bit | R |
| 1204 | Loop 1 | Saved Setpoint | 8Bit | R/W |
| 1205 | Loop 1 | Calculated Setpoint | 8Bit | R |
| 1206 | Loop 1 | Proportional output | 8bit | R |
| 1207 | Loop 1 | Binary output | 8Bit | R |
| 1208 | Loop 2 | Control input state | 8Bit | R |
| 1209 | Loop 2 | Control loop sequence 1 = heating, 0 = cooling | 1bit | R |
| 1210 | Loop 2 | Control input unit | 8 bit | R |
| 1211 | Loop 2 | Control input value | 16bit | R |
| 1212 | Loop 2 | Saved Setpoint | 8Bit | R/W |
| 1213 | Loop 2 | Calculated Setpoint | 8Bit | R |
| 1214 | Loop 2 | Proportional output | 16bit | R |
| 1215 | Loop 2 | Binary output | 8Bit | R |
| 1216 | Loop 3 | Control input state | 8Bit | R |
| 1217 | Loop 3 | Control loop sequence 1 = heating, 0 = cooling | 1bit | R |
| 1218 | Loop 3 | Control input unit | 8 bit | R |
| 1219 | Loop 3 | Control input value | 16bit | R |
| 1220 | Loop 3 | Saved Setpoint | 8Bit | R/W |
| 1221 | Loop 3 | Calculated Setpoint | 8Bit | R |
| 1222 | Loop 3 | Proportional output | 16bit | R |
| 1223 | Loop 3 | Binary output | 8Bit | R |
| 1224 | Loop 4 | Control input state | 8Bit | R |
| 1225 | Loop 4 | Control loop sequence 1 = heating, 0 = cooling | 1bit | R |
| 1226 | Loop 4 | Control input unit | 8 bit | R |
| 1227 | Loop 4 | Control input value | 16bit | R |
| 1228 | Loop 4 | Saved Setpoint | 8Bit | R/W |
| 1229 | Loop 4 | Calculated Setpoint | 8Bit | R |
| 1230 | Loop 4 | Proportional output | 16bit | R |
| 1231 | Loop 4 | Binary output | 8Bit | R |

Analog Outputs

| Address | AO | Description | Range | R/W |
|---------|-----|----------------------------------------------------------------------------------------------|-------|-----|
| 1300 | AO1 | State Bit 0: 0 = not active / error, 1 = ok Bit 1: 0 = automatic mode, 1 = manual mode | 8Bit | R |
| 1301 | AO1 | Current value | 16bit | R |
| 1302 | AO1 | Override value (Only applies if output set to manual) | 16bit | R/W |
| 1303 | AO2 | State, 0 = not active / error, 1 = ok | 8Bit | R |
| 1304 | AO2 | Current value | 16bit | R |
| 1305 | AO2 | Override value (Only applies if output set to manual) | 16bit | R/W |
| 1306 | AO3 | State, 0 = not active / error, 1 = ok | 8Bit | R |
| 1307 | AO3 | Current value | 16bit | R |
| 1308 | AO3 | Override value (Only applies if output set to manual) | 16bit | R/W |

Digital Outputs

| Address | DO | Description | Range | R/W |
|---------|-----|----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------|-----|
| 1400 | DO1 | State Bit 0: 0= Floating mode is OFF, 1 = Floating mode is ON Bit 1: 0= not active / error, 1 = active and ok Bit 2: 0 = automatic mode, 1 = manual mode Bit 3: 0 = PWM not active, 1 = PWM active Bit 6: 0 = Run time totalizer disabled, 1 = Run time totalizer ON Bit 7: 0 = Run time limit not reached, 1 = Run time limit reached Bit 3 to 7 only apply if Bit 0 = 0 (non floating output) | 8Bit | R |
| 1401 | DO1 | Current value | 1bit | R |
| 1402 | DO1 | Override value (Only applies if output set to manual) | 1bit | R/W |
| 1403 | DO2 | State, as on 1400 | 8Bit | R |
| 1404 | DO2 | Current value | 1bit | R |
| 1405 | DO2 | Override value (Only applies if output set to manual) | 1bit | R/W |
| 1406 | DO3 | State, as on 1400 | 8Bit | R |
| 1407 | DO3 | Current value | 1bit | R |
| 1408 | DO3 | Override value (Only applies if output set to manual) | 1bit | R/W |
| 1409 | DO4 | State, as on 1400 | 8Bit | R |
| 1410 | DO4 | Current value | 1bit | R |
| 1411 | DO4 | Override value (Only applies if output set to manual) | 1bit | R/W |
| 1412 | DO5 | State, as on 1400 | 8Bit | R |
| 1413 | DO5 | Current value | 1bit | R |
| 1414 | DO5 | Override value (Only applies if output set to manual) | 1bit | R/W |
| 1415 | DO6 | State, as on 1400 | 8Bit | R |
| 1416 | DO6 | Current value | 1bit | R |
| 1417 | DO6 | Override value (Only applies if output set to manual) | 1bit | R/W |

Fans

| Address | FAN | Description | Range | R/W |
|---------|------|--------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------|-----|
| 1500 | FAN1 | State Bit 0/1:= Current fan output Bit 2: 0= not active / error, 1 = active and ok Bit 3: automatic mode, 1 = manual mode Bit4/5: = Total number of fan speeds Bit 6: 0 = Fan startup delay pending, 1 = fan startup delay expired Bit 7: 0 = no fan alarm, 1 = Fan feedback alarm pending | 8Bit | R |
| 1501 | FAN1 | Current value | 1Bit | R |
| 1502 | FAN1 | Override value | 16bit | R/W |
| 1503 | FAN2 | State, 0 = not active / error, 1 = ok | 8Bit | R |
| 1504 | FAN2 | Current value | 1Bit | R |
| 1505 | FAN2 | Override value | 16Bit | R/W |

Alarms

| Address | ALARM | Description | Range | R/W |
|---------|-------|---------------------------------------------------|-------|------|
| 1600 | ALA1 | Alarm active 0 = not active, 1 = active | 1Bit | R |
| 1601 | ALA1 | Alarm confirmed, 0 = confirmed, 1 = not confirmed | 1Bit | R/W* |
| 1602 | ALA2 | Alarm active 0 = not active, 1 = active | 1Bit | R |
| 1603 | ALA2 | Alarm confirmed, 0 = confirmed, 1 = not confirmed | 1Bit | R/W* |
| 1604 | ALA3 | Alarm active 0 = not active, 1 = active | 1Bit | R |
| 1605 | ALA3 | Alarm confirmed, 0 = confirmed, 1 = not confirmed | 1Bit | R/W* |
| 1606 | ALA4 | Alarm active 0 = not active, 1 = active | 1Bit | R |
| 1607 | ALA4 | Alarm confirmed, 0 = confirmed, 1 = not confirmed | 1Bit | R/W* |
| 1608 | ALA5 | Alarm active 0 = not active, 1 = active | 1Bit | R |
| 1609 | ALA5 | Alarm confirmed, 0 = confirmed, 1 = not confirmed | 1Bit | R/W* |
| 1610 | ALA6 | Alarm active 0 = not active, 1 = active | 1Bit | R |
| 1611 | ALA6 | Alarm confirmed, 0 = confirmed, 1 = not confirmed | 1Bit | R/W* |
| 1612 | ALA7 | Alarm active 0 = not active, 1 = active | 1Bit | R |
| 1613 | ALA7 | Alarm confirmed, 0 = confirmed, 1 = not confirmed | 1Bit | R/W* |
| 1614 | ALA8 | Alarm active 0 = not active, 1 = active | 1Bit | R |
| 1615 | ALA8 | Alarm confirmed, 0 = confirmed, 1 = not confirmed | 1Bit | R/W* |

*) Writable to 0 = confirmed only if state is 1 = not confirmed;

Static Address List

With these addresses the settings may be changed of the controller. They correspond with the parameter settings for the addressed TCX2 controller. The address is calculated by the parameter number of the controller, the number of the function minus 1 and then multiplied with 100 and the table below. For example the address for parameters for universal input 3 start at address: $(3-1) \times 100 + 3000 = 3200$.

| Description | 1 | 2 | 3 | 4 | 5 | 6 | 7 | 8 | 9 | 10 | 11 | 12 |
|-----------------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|-------|
| User settings | 2000 | | | | | | | | | | | |
| Universal input | 3000 | 3100 | 3200 | 3300 | 3400 | 3500 | 3600 | 3700 | 3800 | 3900 | | |
| Control Loop | 5000 | 5100 | 5200 | 5300 | | | | | | | | |
| Analog Output | 6000 | 6100 | 6200 | | | | | | | | | |
| Binary Output | 7000 | 7100 | 7200 | 7300 | 7400 | 7500 | | | | | | |
| Fan output | 8000 | 8100 | | | | | | | | | | |
| Alarm | 9000 | 9100 | 9200 | 9300 | 9400 | 9500 | 9600 | 9700 | | | | |
| Functions | 10000 | 10100 | 10200 | 10300 | 10400 | | | | | | | |
| Time Schedules | 11100 | 11200 | 11300 | 11400 | 11500 | 11600 | 11700 | 11800 | 11900 | 12000 | 12100 | 12200 |
| Communication | 13000 | | | | | | | | | | | |

Time schedule Settings

Time schedules are slightly special as they do not operate with parameters. Time Schedules addresses start at address 11000. To remotely change time schedule settings, follow the table below.

| Address | Module | Description | Range | R/W |
|---------|---------|-----------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------------|-------|-----|
| 11000 | General | Enable time schedules | 1bit | R/W |
| Table+0 | SCHED1 | Time of time schedule event | time | R/W |
| Table+1 | SCHED1 | Active days of time schedule event (bits) Bit 0 = Day 1 (Monday) Bit 1 = Day 2 (Tuesday) Bit 2 = Day 3 (Wednesday) Bit 3 = Day 4 (Thursday) Bit 4 = Day 5 (Friday) Bit 5 = Day 6 (Saturday) Bit 6 = Day 7 (Sunday) | 8bit | R/W |
| Table+2 | SCHED1 | Type of time schedule: 0 = Disabled 1 = Operation mode 2 = Control loop setpoint 3 = Analog output setpoint 4 = Fan output 5 = Binary output | 8bit | R/W |
| Table+3 | SCHED1 | ID of time schedule: Will show only if type of schedule is not operation mode. | 8bit | R/W |
| Table+4 | SCHED1 | Type of times schedule is operation mode: 0 = OFF, 1 = Economy, 2 = ON For all other types: Setpoint | 8bit | R/W |