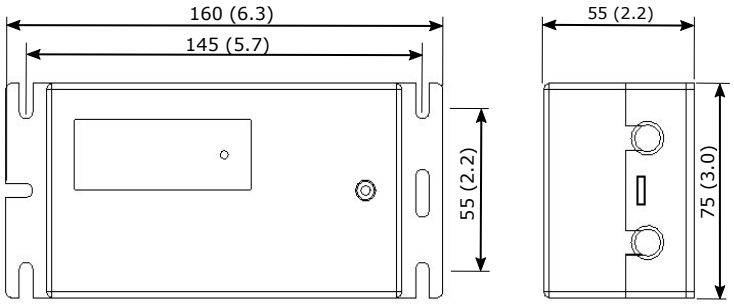
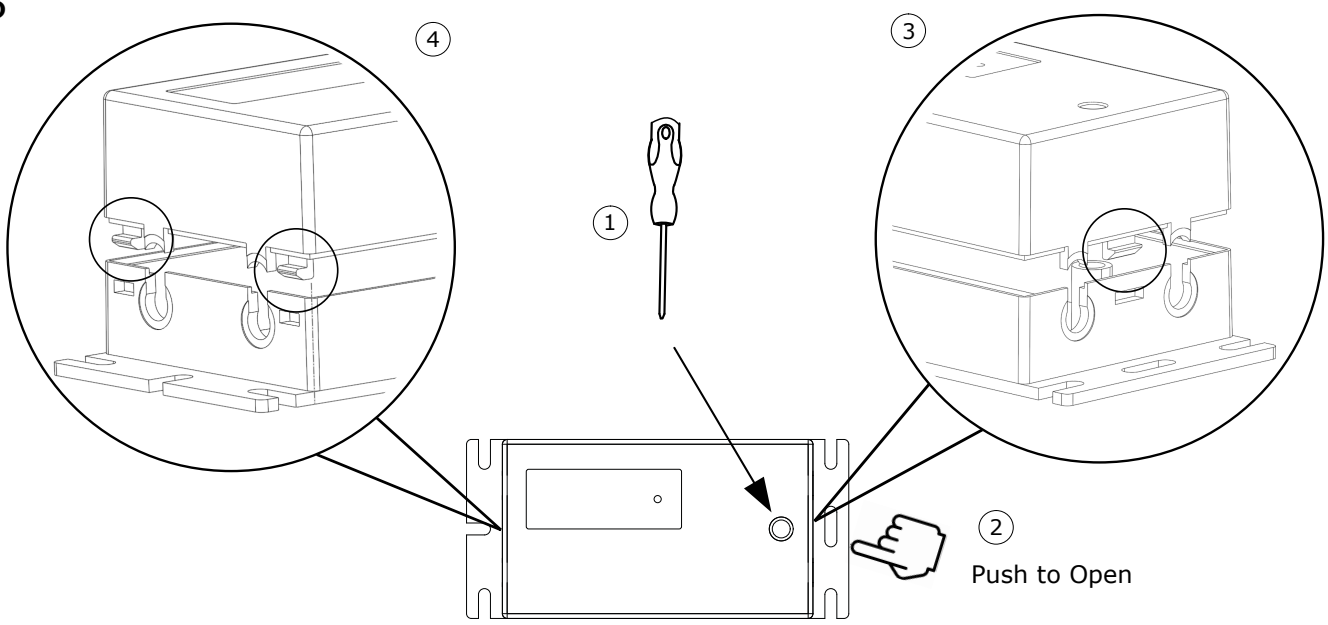
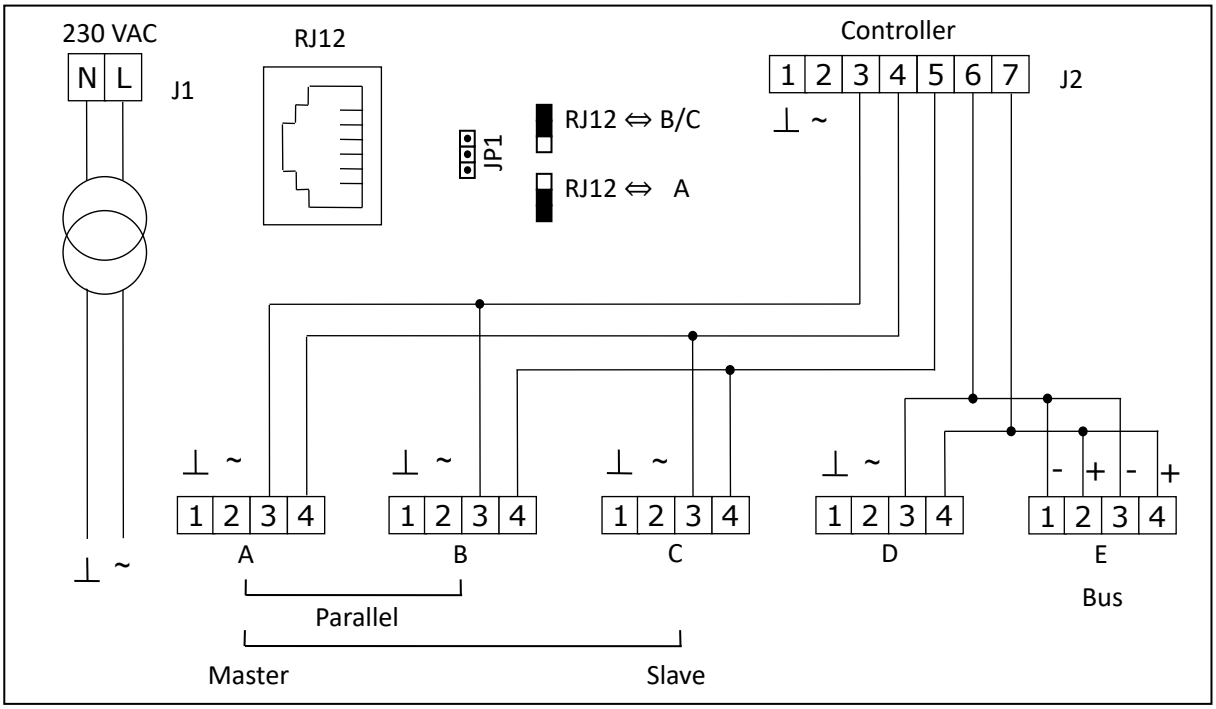
A **mm (inch)**


160 (6.3)
145 (5.7)
55 (2.2)
55 (2.2)
75 (3.0)

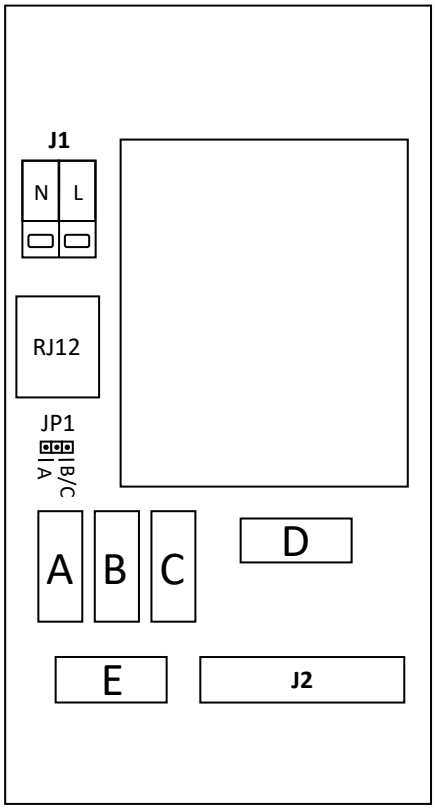
B

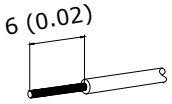

4
3
1
2
Push to Open

C.1


230 VAC
N L
J1
RJ12
JP1
RJ12 ⇔ B/C
RJ12 ⇔ A
Controller
1 2 3 4 5 6 7
J2
⊥ ~
1 2 3 4
A
B
C
D
E
- + - +
Bus
Parallel
Master
Slave

C.2

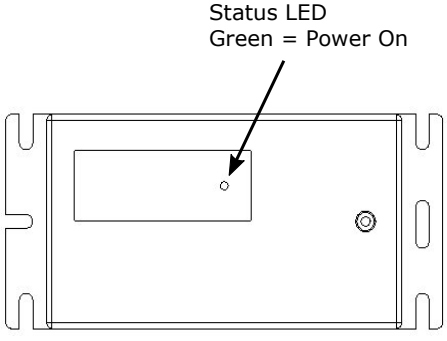




J1	**Speisung 230 V**
J2	**Steuergeräte / Regelsignal** 1 = 24 VAC ⊥ 2 = 24 VAC ~ 3 = 2...10 VDC Regelsignal für Antrieb A und B 4 = Rückführsignal von Antrieb A sowie Regelsignal für Antrieb C 5 = Rückführsignal Antrieb B oder C 6 = Regelsignal Antrieb D 7 = Rückführsignal Antrieb D
RJ12	**Programmiergerät** JP1 – B/C = RJ12 verbunden mit Antrieb B oder C (Abluft) JP1 – A = RJ12 verbunden mit Antrieb A (Zuluft)
A,B,C,(D) A = Zuluft B = Abluft parallel C = Abluft Slave	**Stellgeräte** - Antriebe, VAV Regler 1 = 24 V ⊥ 2 = 24 V ~ 3 = 2…10 V Regelsignal 4 = Rückführsignal
E	**Bus** 1 = - 2 = + 3 = - 4 = +

J1	**Supply 230 V**
J2	**Control unit / control signal** 1 = 24 VAC ⊥ 2 = 24 VAC ~ 3 = 2...10 VDC control signal for drive A and B 4 = Feedback signal from A as well as control signal for C 5 = Feedback signal from B or C 6 = Control signal drive D 7 = Feedback signal drive D
RJ12	**Programming device** JP1 – B/C = RJ12 Connected to Actuator B or C (exhaust) JP1 – A = RJ12 Connected to Actuator A (intake)
A,B,C,(D) A = Intake B = Exhaust parallel C = Exhaust slave	**Actuators** - drive, VAV controllers 1 = 24 V ⊥ 2 = 24 V ~ 3 = 2…10 V control signal 4 = Feedback signal
E	**Bus** 1 = - 2 = + 3 = - 4 = +

D



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